

Fig 3 Perturbation flow field along line  $l$  (planar boundary condition approximation);  $M_\infty = 0.4$ ,  $\alpha = 6^\circ$

thickness case, the results for Cases A and B match closely. Thus, no dense wing leading-edge paneling is required as far as the lift induced flow field is concerned. The effect of the wing leading edge paneling on the thickness induced flow field is determined by comparing Cases A and B for the data obtained with thickness taken into account. As Fig 3 shows that the influence of the wing thickness on the flow field is severe, particular attention is required. Figure 3 demonstrates the trivial result that the differences in the perturbation velocities obtained with  $KI=3$  (round nose) and  $KI=1$  (sharp nose) are small if the leading edge region is paneled more densely (Case B). However, for a coarse leading edge paneling (Case A), these differences become very significant, the correct leading edge definition ( $KI=3$ ) yielding correct results, whereas the  $KI=1$  results are totally unacceptable. Thus, as far as the thickness induced flow field is concerned, no dense wing leading edge paneling is required provided that the roundness of the leading edge is taken into account properly.

### Conclusions

As to the modeling of carrier aircraft wings in external store load calculations using the panel method, it was demonstrated for a particular wing with round leading edge that:

- 1) The planar boundary condition approximation may be applied to the aircraft wing.
- 2) Wing thickness may not be ignored.
- 3) Using the planar b.c. approximation, a coarse paneling of the aircraft wing leading edge region is allowed, provided the leading edge roundness is incorporated properly in the source strengths representing the aircraft wing thickness.

Although these conclusions have been demonstrated using particular codes (USSAERO, USTORE), they should have a much more general validity.

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## A Nonlinear Analysis of the Cushion Stability of Slowly Oscillating ACV's

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### Introduction

THE main dynamic effects which would appear in the fan duct plenum system of ACV's might be enumerated as: 1) unsteady operating characteristics of the fan, 2) unsteady flow in the ducting, 3) wave propagation phenomena in the

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ducting and 4) unsteady flow in the cushion. The third effect may be generally involved in the second effect but it is separated here for convenience. Goldschmied and Wormley,<sup>1</sup> and Hinchy and Sullivan<sup>2</sup> considered effect (1) but in most cases a quasistatic characteristic of the fan has been assumed since with relatively low oscillation frequency as in marine ACV's this effect is not significant.<sup>3</sup> On this assumption, Hinchy and Sullivan<sup>4</sup> investigated effects (2) and (3) and reported that the general effect of the air inertia, inertance of the duct flow, was important even for relatively short ducts. Durkin and Luehr<sup>5</sup> investigated effect (2) in the volute flow of fans. An earlier study by Yano and Nagayama<sup>3</sup> employed a similar method for the analysis of the scavenging system of the diesel engine. Goldschmied and Wormley,<sup>1</sup> Sweet, Richardson and Wormley,<sup>6</sup> and at a later time Hinchy and Sullivan<sup>2,4</sup> investigated effect (3) solving one dimensional acoustic equations. It is very difficult to rigorously analyze effect (4). In most instances, however, the air in the cushion is in a reservoir condition, thus obviating the need to analyze this effect.

In this report an ACV with comparatively low cushion pressure and low oscillation frequency is assumed. This is usually the case with conventional marine ACV's. Therefore, it may be sufficient here to consider a lumped inertance as the effect (2). The purpose of this report is to extend previous quasisteady analyses<sup>7,8</sup> to a nonlinear analysis of large amplitude oscillation including the effect (2). The compressibility of air is also considered in the quasisteady analysis of the flow in the duct and the cushion but in the present case where the cushion pressure is relatively small (around 10 psf) its effect has proven to be negligible. A forced oscillation test of the fan duct plenum model was performed.<sup>8</sup> The analytical results have been in good agreement with the experimental results. This is noticeable when the inertance in the duct flow is considered. The discrepancy (in a frequency range higher than 1 Hz), which appeared in the previous quasisteady analysis,<sup>8</sup> has disappeared. The theoretical and experimental results are, therefore, nearly identical.

### Analysis and Discussion

We assume a quasisteady change except for the flow through the ducting. For the continuity of the flow in and out

of the cushion we have

$$Sh/c = Q_f/c - hC_d\sqrt{2P_c/\rho} \quad (1)$$

where  $P_c$  is the cushion pressure;  $Q_f$  the volume flow rate of the fan;  $\rho$  the density of air assumed constant for the present;  $h$  the hoverheight;  $C_d$  the discharge coefficient; and  $c$  the peripheral length of the effective base area  $S$ . The prime represents a derivative with respect to time  $t$ .

The quasisteady characteristics of the fan and the powerplant are represented as

$$P_f = P_f(Q_f, n_f) \quad (2)$$

$$T_f = T_f(Q_f, n_f) \quad (3)$$

$$T_p = T_p(n_p) \quad (4)$$

where  $P_f$  is the total pressure just behind the fan;  $T_f$  and  $T_p$  the input torque of the fan and the output torque of the powerplant, respectively; and  $n_f$  and  $n_p$  the rotational speeds of the fan and the powerplant respectively.

$$J_f \dot{n}_f = T_{sf} - T_f \quad (5)$$

$$J_p \dot{n}_p = T_p - T_{sp} \quad (6)$$

where  $T_{sf}$  and  $T_{sp}$  are actual torques affected by the rotary inertia and  $J_f/(2\pi)$  and  $J_p/(2\pi)$  are the moments of inertia.

Assuming the reduction ratio  $\kappa$  and the transmission efficiency  $\eta_t$  we have

$$n_p = \kappa n_f \quad (7)$$

$$T_{sf} = \kappa \eta_t T_{sp} \quad (8)$$

We assume that the air in the ducting is incompressible and that the flow is one dimensional and unsteady. From the conservation law of momentum we have<sup>9</sup>

$$\frac{d}{dt}(\rho S_f u \delta x) = -\frac{\partial}{\partial x}(PS_f) \delta x - \pi f D (\rho u^2/2) \delta x \quad (9)$$

where  $u$  is the flow velocity and  $P$  the fluid pressure;  $S_f$  the fan exit area and  $D$  the diameter of the duct; and  $f$  the wall friction coefficient. Integrating Eq. (9) over the full length of the duct we have

$$(\rho L/S_f) \dot{Q}_f = P_f - P_c - \zeta(\rho/2)(Q_f/S_f)^2 \quad (10)$$

where  $L$  is the duct length and  $\zeta$  is defined as

$$\zeta = 4fL/D \quad (11)$$

From Eqs. (1), (2) and (10) we have the expression

$$G_1(\dot{Q}_f, Q_f, n_f; h, \dot{h}) = 0 \quad (12)$$

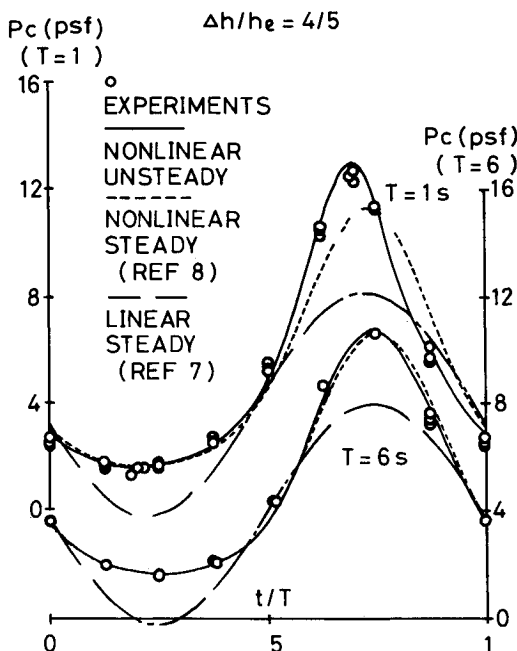


Fig 1 Variation of cushion pressure with time

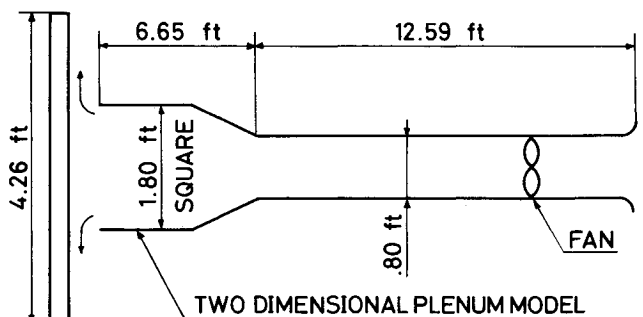


Fig 2 A sketch of experimental setup

while from Eqs (3 8)

$$G_2(Q_f \dot{n}_f n_f) = 0 \quad (13)$$

Equations (12) and (13) form a system of nonlinear differential equations. When  $h(t)$  is known, it can be numerically integrated with appropriate initial conditions. If we only wish to seek the steady state solutions, the initial conditions can be chosen arbitrarily. To simplify the procedure, we define nondimensional quantities such as

$$\xi = 4Q_f / (\pi^2 d^3 n_f) \quad (14)$$

$$\psi = \psi(\xi) = 2P_f / (\rho \pi^2 d^2 n_f^2) \quad (15)$$

$$\lambda_f = \lambda_f(\xi) = 16T_f / (\rho \pi^3 d^5 n_f^2) \quad (16)$$

$$\lambda_p = \lambda_p(n_f) = 16T_p / (\rho \pi^3 V^{5/3} n_p^2) \quad (17)$$

where  $V$  is a characteristic volume of the powerplant and  $d$  the diameter of the fan.

Substitution of Eqs (14) to (17) into Eqs (12) and (13) leads to

$$g_1(\dot{n}_f, n_f, \xi, h) = 0 \quad (18)$$

$$g_2(\dot{n}_f, n_f, \xi) = 0 \quad (19)$$

where

$$g_1 = \psi - \frac{Ld}{2Sn_f^2} \xi \dot{n}_f - \frac{Ld}{2Sn_f} \xi - \left[ \frac{\xi}{2S_f^2} + \frac{1}{2(cC_d h)^2} \right] \frac{\pi^2 d^4}{8} \xi^2 + \frac{Sh}{(cC_d h)^2} \frac{d}{2n_f} \xi - \frac{1}{\pi^2 d^2 n_f^2} \left( \frac{Sh}{cC_d h} \right)^2 \quad (20)$$

$$g_2 = \frac{16(J_f + \kappa^2 \eta_f J_p)}{\rho \pi^3 d^5} \frac{\dot{n}_f}{n_f^2} - \kappa^3 \eta_f \frac{V^{5/3}}{d^5} \lambda_p + \lambda_f \quad (21)$$

Equations (18) and (19) were solved using the fourth order Runge Kutta method with intervals of 0.001 s in  $t$ .  $\psi(\xi)$  and  $\lambda_f(\xi)$  were approximated by polynomials of seventh and third order in  $\xi$  respectively, using the method of least squares.  $\lambda_p(n_f)$  was similarly approximated by a polynomial of the third order in  $n_f$ . A simple harmonic oscillation

$$h = h_e + \Delta h \sin(2\pi t/T) \quad (22)$$

is assumed. To confirm the independence of the steady state solutions of the initial conditions, computation was made for several cases with the same  $T$  and  $\Delta h/h_e$  but with different initial conditions. The results have been compared with the previous linear<sup>7</sup> and nonlinear<sup>8</sup> quasisteady solutions and the experimental results.<sup>8</sup> Results are shown in Fig. 1. A sketch of the experimental setup is shown in Fig. 2. The plenum oscillates horizontally and the instantaneous cushion pressure and the hoverheight are measured electrically. The details of the experiment and of the method of analysis are discussed in Ref. 8. Experiments were made for  $T \geq 1$  s and  $\Delta h/h_e \leq 0.8$ . The mean hoverheight  $h_e$  was kept at 0.984 in (25 mm) throughout. As  $T$  decreases (and as  $\Delta h/h_e$  increases) the discrepancy between the quasisteady solution and the experimental results become noticeable.<sup>8</sup> The present nonlinear unsteady solution gives good results. A quasisteady consideration of the compressibility of air was also made using the method employed by Yano and Nagayama.<sup>4</sup> In the present study the difference has been so small that it cannot be clearly represented graphically. It can almost be concluded that the inertance of air in the duct is the dominant unsteady effect in the present study.

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## An Inverse Solution for Component Positioning Using Homogeneous Coordinate Transformations

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## Introduction

**H**OMOGENEOUS coordinate transformations are used widely in computer graphics and aircraft computer aided conceptual design.<sup>1,3</sup> They are used to create orthographic and perspective views and also can be used to allow local axis systems for the separate components which comprise the aircraft three dimensional data base. In such an application each component's local axis system is defined by six parameters; i.e.,  $x_i, y_i, z_i$  (origin offset), and roll, pitch and yaw (axis orientation). Matrix operations are used to transform the points or equations which describe the component into the global axis system. These matrix operators are the  $3 \times 3$  direction cosine relationships which are a subset of the homogeneous coordinate transformations.

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